

Lecture 4 – Flutter: Part 1 Equations of Motion

We will begin the first topic of _____ with the study of _____ of an _____ in a _____.

Dynamic Aeroelasticity

It is the study of _____ of a structure subjected to aerodynamic forces, in another words, the _____ of the structure. As we know, the aerodynamic forces depend on the structural orientation and deformation, so the equations of motion of such structures involve _____ the dynamic aerodynamic loadings with structural dynamics.

Flutter Phenomena

Flutter is one of the most dramatic aeroelastic phenomena. One of the most well known engineering catastrophes is the structural failure of the Tacoma Narrows Bridge in 1940. See example here <http://www.youtube.com/watch?v=j-zczJXSxw>. (Highly recommended)

Although the application of flutter analysis will apply to most structures that oscillate when exposed to a fluid flow, we will limit our attention to an aerofoil section here.

For simplicity, we will use a typical _____ aerofoil shown in figure 1 in our studies. It is a rigid two dimensional symmetric aerofoil with zero initial twist ($\alpha_r = 0$). Structural damping is neglected here.

Figure 1

L	Lift force
M_{ac}	Pitching moment at the aerodynamic centre
α	Aerofoil twist angle (measured from horizontal and positive nose up)
h	Vertical displacement (measured at elastic axis and positive downward)
U	Free stream velocity
c	Chord length
k_h	Spring stiffness in vertical translation
k_α	Spring stiffness in rotation

Equations of Motion

We will use _____ to determine the equations of motion of the aerofoil in figure 1. Neglecting the damping terms, we obtain

_____ [EQN.1]

where the terms in equation 1 are

T	Total kinetic energy
U	Total potential energy
\mathbf{q}	Generalised coordinates, in this case $\mathbf{q} = \begin{Bmatrix} h \\ \alpha \end{Bmatrix}$
\mathbf{Q}	Generalised forces, in this case $\mathbf{Q} = \begin{Bmatrix} -L \\ M \end{Bmatrix}$
t	Time in seconds

Total Kinetic Energy

Let us consider a _____ of the aerofoil at _____ with _____ (*see figure 1*).

Assuming that the twist angle is small, the _____ of the element is given by

Let m' denote the mass per unit length (chord wise), the kinetic energy for one element is given by

Hence the total kinetic energy of the aerofoil is given by

_____ [EQN.2]

Note that

$\int m \ddot{x} dx =$	
$\int m \dot{x}^2 dx =$	
$\int m \dot{x} dx =$	

Finally, we can rewrite equation 2 to show that the total kinetic energy of the aerofoil is given by

$$\text{_____} \quad \text{[EQN.3]}$$

Total Potential Energy

Only potential energies stored in the springs are included here

$$\text{_____} \quad \text{[EQN.4]}$$

Generalised Forces

The force and moment in the directions of the general coordinates are negative lift and pitching moment respectively. For a symmetric aerofoil at _____ angles of attack, _____. We normally write aerodynamic forces in their nondimensional forms, hence we obtain

$$\text{_____} \quad \text{[EQN.5]}$$

$$\text{_____}$$

where we use the same nomenclatures as the previous chapters, i.e.

$q = \frac{1}{2} \rho U^2$	Dynamic pressure
S	Wing area (chord x span)
x_{ac}	Distance between CG and elastic axis (positive when elastic axis is ahead of CG)

Equations of Motion of a 2-dof Aerofoil

Finally, differentiate equations 3, 4 and 5 with respect to _____ and _____, and substitute those expressions into equation 1 to obtain the following equilibrium equations

$$\text{_____} \quad \text{[EQN.6]}$$

$$\text{_____}$$

Rewriting the above equations in matrix form, we obtain

$$\text{_____} \quad \text{[EQN.7]}$$

with

$\mathbf{M} = \begin{bmatrix} m & mx_{CG} \\ mx_{CG} & I_\alpha \end{bmatrix}$	
$\mathbf{K} = \begin{bmatrix} k_h & 0 \\ 0 & k_\alpha \end{bmatrix}$	
$\mathbf{A} = S \begin{bmatrix} 0 & C_{L\alpha} \\ 0 & x_{ac} C_{L\alpha} \end{bmatrix}$	

We will study the stability of the aeroelastic system by analyzing the _____ of equation 7 in the next lecture.